Midterm Review: Distributed Algorithms

Chapter 1. Introducation

Attributes of distributed algorithms:

Interprocess communication method: shared-memory, point-to-point, and broadcast

The timing models:

Synchronous (lock-step synchrony), completely asynchronous, and partial asynchronous.

The failure models:

Stopping failures vs. Byzantine failures

Distributed algorithms vs. concurrent algorithms:

Higher degree of uncertainty and more independence of activites

Unknown # of processes, unknown network topology, several programs executing at once, starting at different times, and operating at different speeds, processor non-determinism, uncertain message delivery times, unknown message ordering, and processor and communication failures.

Four models:

Synchronous model, asynchronous model (shared memory vs. network), and partially synchronus (timing-based) model.

Chapter 2. Synchronous Network Model

Chapter 3. Leader Election

Algorithms:

LCR HR (O(n log n) communication complexity) Timeslice (non-comparison-based with known n) VariableSpeeds (non-comparison-based with unknown n)

Chapter 4: Algorithms

Algorithms:

FloodMax OptFloodMax (reducing comm. complexity) SynchBFS (breadth-first tree) BellmanFord (shortest path) General strategy for MST (minimum spanning tree) SynchGHS LubyMIS (maximal independent set, winner, lser, and losers' neighbors) Chapter 5 Distributed Consensus with Link Failures

Agreement-Validity-Termination

Impossibility result

Chapter 6. Distributed Consensus with Process Failures

Stopping failure vs. Byzantine failure (Weak) validity condition vs. stronger validity condition

Algorithms

FloodSet (stopping failure) OptFloodSet (broadcast at most two values) EIG (Exponential Information Gathering): EIGStop OptEIGStop (broadcast at most two values) EIGByz (Binary Byzantine failure) TurpinCoan (General Byzantine failure) Byzantine Agreement in General Graphs (connectivity requirement) Weak Byzantine Agreement

Chapter 7: More Consensus Problems

Algorithms

ByzApproxAgreement (Approximate Agreement)

Chapter 9* Asynchronous Shared-Memory Model

Chapter 14 Asynchronous Network Model

Chapter 15 Asynchronous Network Algorithms

Algorithms

AsynchLCR PetersonLeader (unidirectional ring) AsynchSpanningTree AsynchBcastAck (convergecast) STtoLeader (leader election in an unrooted spanning tree) AsynchBFS LayeredBFS HybridBFS AsynchBellmanFord GHS (merge and absorb) SimpleMST

Chapter 16. Synchonizers

Algorithms

GlobSynch LocSynch SimpleSynch (virtual round) SafeSynch (Opt version) Alpha synchronizer Beta synchronizer Gamma synchronizer

Chapter 17. Shared Memory vs. Networks

Two models (with fault tolerance) are pretty much the same.